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HV-D27A  
HV-D37A

Color Camera  
Tentative Specifications

DWN	K.Tanaka	Jun・6・'04	HV-D27A/HV-D37A Color Camera Tentative Specification (1/17)	Hitachi Kokusai Electric Inc Tokyo Japan	
DSGN	K.Tanaka	Jun・6・'04			
CHKD	T.Inoue	Jun・6・'04			
APPD	T.Inoue	Jun・6・'04			

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1. General

HV-D27A/HV-D37A color camera is a separate type camera head utilizing three CCDs in a compact and light weight and camera control unit (CCU) system. By utilizing 410,000 pixels (470,000 pixels PAL) CCDs in addition to single LSI chip digital circuit construction from processor to encoder, both high picture quality and high stability have been achieved. CCD size is 1/2-inch for the HV-D27A and 1/3-inch for the HV-D37A.

Hitachi's extensive experience in broadcast and industrial color cameras has lead to an exclusive 14-bit digital processing technology that provides a host of important functions in a newly developed LSI device. The high quality signal processing and image compensating functions were unattainable in earlier analog cameras. The versatile C mount also allows use with a broad range of optical systems and opens up applications in a wide variety of fields, factory automation, image processing, microscope technology etc.

2. Features

1) Single chip LSI camera signal processor

Hitachi's leading edge processing technology (0.18 μm, internal core 1.8V drive, and 3 million gates) is contained on a single newly developed ultra LSI chip. The system is compact and consumes very little power. Also, the 12-bit A/D converter and 14-bit internal processor provide high signal to noise ratio and wide dynamic range.

2) C mount

The camera uses a C mount lens, which is the de facto standard in the industry.

Note : Some lenses cannot be used. Check before use. See "9 when using lens".

3) High resolution

The 410,000 pixel (470,000 PAL) CCDs with high sensitivity microlenses are mated to prism optics using high precision matching technology. Accelerated digital luminance signal processing is used to deliver 800 TV lines (HV-D27A) / 750 TV lines (HV-D37A) horizontal resolution (luminance channel).

4) High S/N

A signal to noise ratio of 62 dB (60dB PAL) is attained by the new digital noise reduction system. Clear, low noise images are obtained even in the high gain mode.

5) High sensitivity

The +24 dB high gain mode and digital gain function provide sensitivity and low light performance 0.5lx, F1.6 (HV-D27A)/0.9lx, F2.2 (HV-D37A). When combined with the digital noise reduction system, pickup is enabled under adverse conditions that were beyond the reach of previous CCD cameras.

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## 6) Digital processing enables quality enhancement functions

- Extensive experience in broadcast and industrial cameras is evidenced by the 6 vector independent variable masking, which is ideal for such applications as image processing and microscope technology where high color reproduction fidelity is essential.
- Auto knee varies the high luminosity signal compression point according to the amount of incident light. Dynamic chroma compensates for color loss in high luminosity signals. Dynamic range is expanded to bring high reproduction quality even to outdoor scenes.
- Variable detail boost frequency is also provided.

## 7) Auto shading compensation (ASC)

Color shading incurred when using a C mount lens is automatically compensated (attenuated).

Two modes of shading are provided and can be selected according to the cameras application, a vertical color shading mode or a two-dimensional luminance-shading mode.

## 8) CCD drive functions

- Preset electronic shutter mode (10 steps)
- Lockscan mode reduces flicker in images with a different scanning frequency (e.g., a scene showing a computer display screen). The fixed frequency minimizes the appearance of a horizontal bar (not effective in all cases).
- Auto electronic shutter (AES) maintains a fixed video level.
- Long term integration mode accommodates field and frame integration (needs external video memory for a continuous picture).
- Frame readout mode improves vertical resolution. (The sensitivity lower in AES mode of frame integration.)
- Field on demand produces an image in response to an external trigger signal. (needs external video memory for a continuous picture).

## 9) Versatile pickup functions

- Four scene files  
Detail, masking, knee and other settings can be customized.
- Real time automatic white balance adjustment. The variable detector gate function can be utilized to avoid white balance disruption even if a light source having a different color temperature enters the scene.
- Intelligent ALC (auto level control)  
The digital light meter and CPU processing provide continuous digital control of AGC, lens iris and auto electronic shutter over an extremely wide variation in lighting. The ALC level can be fine adjusted and the response selected for peak or average from the menu.  
(Combining with AES is effective only with a manual override lens.)
- Full auto mode
- AGC and 1 step programmable gain switch

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- Contrast function
- Flare compensation circuit
- Variable chroma level
- Variable master black, R/B black, R/B gain
- Monochrome mode
- Color bar
- Title display
- Negative/positive selection
- Focus data output (Serial data output via RS-232C)

10) Bi-directional data transfer

A personal computer can be connected directly (RS-232C) for remotely controlling the camera functions. Conversely, the camera mode data are sent to the computer to allow very precise camera control. In multiple camera systems, each camera can be assigned an ID number to enable controlling multiple cameras from a single computer.

11) Switchable video signal outputs

The output can be selected for VBS, Y/C, RGB, Y/R-Y/B-Y according to the application.

3. Standard composition

3-1. Camera(HV-D27A/HV-D27A)	.....	1
3-2. Accessories		
1) Lens mount sheet	.....	1
2) Power supply plug (R03-P3F)	.....	1
3) Operation manual	.....	1

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## 4. Specifications

1) Color system	NTSC, PAL	A
2) Optical system	HV-D27A: 1/2-inch, F1.6 prism HV-D37A: 1/3-inch, F2.2 prism	
3) Imaging system	R, G, B 3 CCD	
4) Picture elements	HV-D27A: 1/2-inch interline transfer CCD HV-D37A: 1/3-inch interline transfer CCD (with microlenses)	
Total pixels	NTSC 811 (H) × 508 (V) PAL 795 (H) × 596 (V)	B
Effective pixels	NTSC 768 (H) × 494 (V) PAL 752 (H) × 582 (V)	
Effective image area	HV-D27A: NTSC 6.34 (H) × 4.76 (V) mm PAL 6.35 (H) × 4.78(V) mm HV-D37A: NTSC 4.79 (H) × 3.60 (V) mm PAL 4.80 (H) × 3.60(V) mm	
5) Scanning system	2:1 interlace	
6) Scanning frequency	NTSC 15.735 kHz (H) × 59.94 Hz (V) PAL 15.634 kHz (H) × 50.00 Hz (V)	C
7) Encoder system	R-Y/B-Y	
8) Sync system	Internal/external (VBS, BBS or HD/VD auto selection, when internal input/output switch is input position)	
9) Horizontal resolution	HV-D27A: 800 TV lines, luminance signal center HV-D37A: 750 TV lines, luminance signal center (Y out and DTL off)	
10) S/N	HV-D27A: NTSC 62 dB type (DNR on), 59 dB type (DNR off) PAL 60 dB type (DNR on), 57 dB type (DNR off) (Y out, $\gamma=1$ , DTL off, GAIN 0 dB)	D
11) Standard sensitivity	2000 lx, F11	
12) Minimum illumination	HV-D27A: 0.5 lx (50IRE F1.6) HV-D37A: 0.9 lx (50% F2.2) (GAIN +24 dB, DIGITAL GAIN +12 dB)	
13) Gamma correction	0.45/1.0 (on/off)	
14) Geometric distortion	Full screen 0% (not including lens characteristics)	E
15) Registration	Full screen 0.05% (not including lens characteristics)	
16) Vertical contour compensation	2H	

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17)	Lens mount	C mount (flangeback 17.526 mm in air)						A
18)	Sensitivity selection	AGC (0 to +24 dB) or GAIN (0 to +24 dB step 1dB or step 3 dB on remote control menu)						
19)	Detail control	DTL level and frequency						B
20)	Scene files	4 Files						
21)	Digital gain	+6 dB, +12 dB sensitivity increase by digital signal processing						C
22)	CCD drive functions	Preset: 1/100 (1/60 PAL), 1/250, 1/500, 1/1000, 1/2000, 1/4000, 1/10,000 1/20,000 1/40,000 1/100,000second						
	Lockscan:	NTSC 1/60.38 to 1/2039 second (step 1H), to 1/100,000 second (step approx. 10% video level)						D
		PAL 1/50.31 to 1/2024 second (step 1H) to 1/100,000 second (step approx. 10% video level)						
	AES:	Off to approx. 1/100,000 second						E
	Long term integration:	Field/frame integration selectable						
	Field integration	NTSC 1/30 to approx. 4 seconds (1 frame steps)						F
		PAL 1/25 to approx. 4 seconds (1 frame steps)						
	Frame integration	NTSC 1/30 to approx. 8 seconds (1 frame steps)						
		PAL 1/25 to approx. 8 seconds (1 frame steps) (external image memory needed for continuous image)						
	Frame readout	improves vertical resolution (residual image response deterioration)						
23)	Color bar	NTSC: SMPTE, PAL: Full						
24)	Power supply voltage	12 V rated (Stable operation at 10.5 to 15 VDC (ripple and noise absent))						
25)	Power consumption	Approx. 6.5 W						
26)	Dimensions	HEAD: 38.5(W)×46(H)×42(D)mm CCU: 150(W)×45(H)×170(D)mm						
27)	Mass	HEAD: Approx. 90 g (not including lens) CCU: Approx. 950g						
28)	Ambient temperature	Operating 0 to 45 °C Storage -20 to 60 °C						
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		• •	(6/17)					

## 5. Input and output signals

### 5-1. Input signal conditions

#### 1) Genlock input (MULTI connector)

- VBS 1.0 V<sub>p-p</sub> ±3 dB or black burst/75 Ω or high (BNC)  
(sync 0.3 ±0.1 V<sub>p-p</sub>, burst 0.3 ±0.1 V<sub>p-p</sub>)
- HD/VD 2 to 5 V<sub>p-p</sub>, negative (D-sub connector)

Note: Genlock input and Sync output are selected by internal input/output switch.

#### 2) External trigger input (MULTI connector)

Ext Trig Low 0 VDC, High 2 to 5 VDC

#### 3) Serial data (REMOTE connector)

1.5 V<sub>p-p</sub> ±3 dB/High (when connected to RC-Z3, JU-C20, JU-Z2)  
RS-232C level (when connected to personal computer)

Note: Set internal switches according to connected equipment.)

A level converter JU-C20 is required if controlling the camera from a personal computer via RS-232C interface over a distance more than approx.15 meter.

### 5-2. Output signal ratings

#### 1) Component video output (VIDEO, MULTI connector)

VBS 1.0 V<sub>p-p</sub>/75 Ω

#### 2) Y/C output (Y/C connector, MULTI connector)

Y: 1.0 V<sub>p-p</sub>/75 Ω

C: NTSC 0.286 V<sub>p-p</sub> (burst)/75 Ω

PAL 0.3 V<sub>p-p</sub> (burst)/75 Ω

#### 3) Component output (MULTI connector)

Y: 1.0 V<sub>p-p</sub>/75 Ω

R-Y/B-Y: 0.7 V<sub>p-p</sub>/75 Ω

#### 4) RGB output (MULTI connector)

RGB: 0.7 V<sub>p-p</sub>/75 Ω

Note: YC/VBS, component and RGB MULTI connector outputs are selected by menu.

#### 5) Sync outputs (MULTI connector)

HD/VD: 2 V<sub>p-p</sub>/75 Ω

Sync: 2 V<sub>p-p</sub>/75 Ω

Note: Genlock input and Sync output are selected by internal input/output switch.

#### 6) Serial data output (REMOTE connector)

1.5 V<sub>p-p</sub>/Low (when connected to RC-Z3, JU-C2-, JU-Z2)

RS-232C level (when connected to personal computer)

Note: Set internal switches according to connected equipment.)

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6. External trigger signal timing

6-1. Pulse width control

1) Field on Demand (SHUTTER : EXT TRIG, EXT TRIG : MODE1, CCD MODE : FIELD)  
 The exposure time is controlled by external trigger pulse width. One field of the picture is obtained after SYNC reset. However, the exposure time must not be below 1/1,000s, even the minimum trigger pulse width.

The diagram illustrates the timing relationship between various signals during an external trigger event. Key features include:

- EXT TRIGGER:** A pulse whose width determines the exposure time. A note indicates it must be "more than 64 μs" and is "\*Possible to change polarity".
- V.SYNC:** Shows a "SYNC reset" event occurring during the trigger pulse.
- SHUTTER PULSE:** A single pulse that occurs after the SYNC reset.
- READOUT PULSE:** A single pulse occurring later in the sequence.
- EXPOSURE TIME:** A shaded area representing the duration of the exposure, calculated as "EXPOSURE TIME = TRIG. PULSE WIDTH + MAX 64 μs".
- VIDEO OUT:** Shows the resulting video signal, with a shaded area indicating the exposure period. For NTSC, the duration is labeled "NTSC:20H". For PAL, it is labeled "PAL :25H".
- WE PULSE:** A pulse that is "\*Possible to change polarity" and occurs during the exposure period.
- HD:** Horizontal sync pulses are shown for both NTSC and PAL modes.
- SHUTTER PULSE:** For NTSC, there is a "SYNC reset 2 to 3H delay". For PAL, there is a "SYNC reset 2.5 to 3.5H delay".

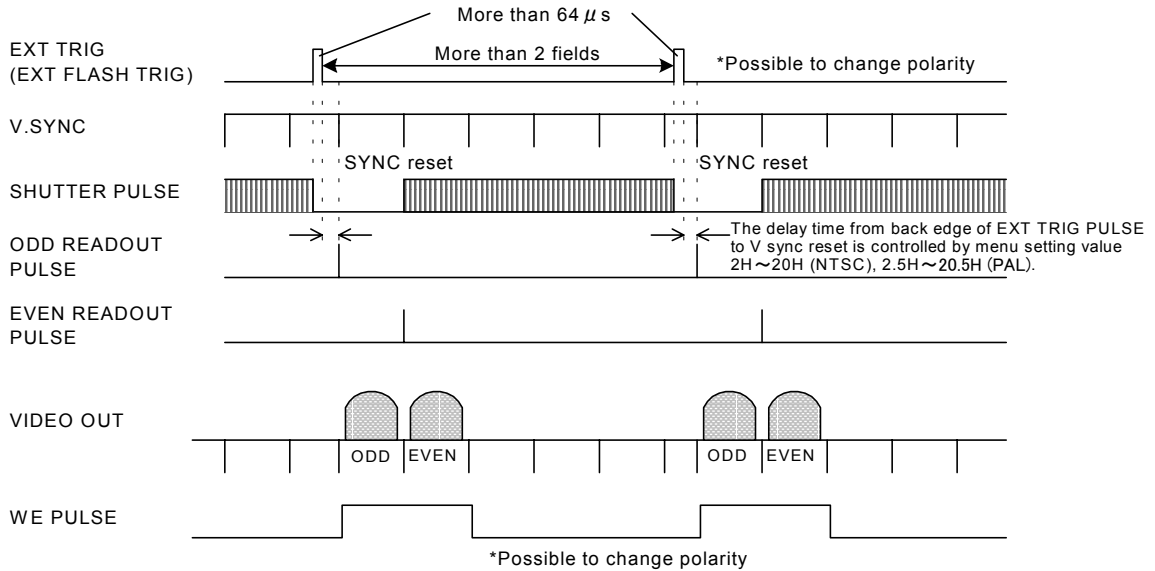
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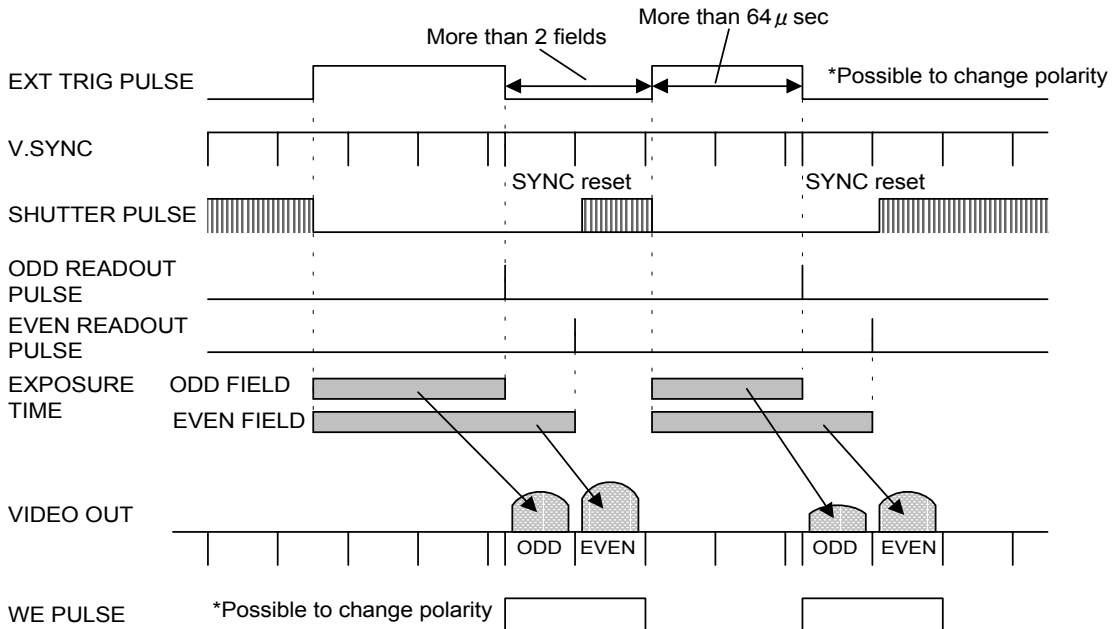


2) Frame on demand (SHUTTER : EXT TRIG, EXT TRIG : MODE1, CCD MODE : FRAME)

When an external flash trigger signal is applied, the V SYNC is reset and one frame of the picture is obtained. The exposure time is controlled by the external trigger pulse width and SYNC reset timing. Also, the SYNC reset timing from the flash timing can be adjusted by the camera menu setting.



Note: When the flashlight is not used, the even and odd video signal levels are difference as shown to the following timing chart.



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6-2. Long integration mode

(1) Field mode (SHUTTER : EXT TRIG, EXT TRIG : MODE2, CCD MODE : FIELD)

The trigger pulse width and the timing of external trigger pulse against the camera SYNC control the exposure time. One field of the picture is obtained at first ODD field after the back edge of external trigger pulse.

(2) Frame mode (SHUTTER : EXT TRIG, EXT TRIG : MODE1, CCD MODE : FRAME)

The trigger pulse width and the timing of external trigger pulse against the camera SYNC control the exposure time. One frame of the picture is obtained at first ODD field after the back edge of external trigger pulse.

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Note: For each external trigger mode, when the end edge of external trigger pulse is input in the timing period when it showed to the under figure, the picture is not output after the SYNC reset. Please input the repetition period of trigger pulse with the following specification, to avoid the trigger input to an above prohibition period.

The period of the next end edge trigger pulse from the before end edge of trigger  
 CCD MODE: FLD, except from  $nV$  to  $nV+2H$   
 CCD MODE: FRM, except from  $2nV$  to  $2nV+2H$   
 (V: a vertical synchronous period, n: an integer)

EXT TRIGGER

CAMERA SYNC

SYNC reset timing

Next SYNC Reset timing

Prohibition period of the end edge of external trigger pulse (1H period before the start of camera V SYNC)

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## 7. Connectors

(1) MULTI connector  
(SDEB-9S)

Pin No	Signal
1	GND
2	WE
3	R OUT
4	G OUT
5	B OUT
6	VBS OUT
7	SYNC OUT
8	RESERVE
9	RESERVE

(2) REMOTE connector  
(HR10A-7R-4S) (Plug: HR10A-7P-4P)

Pin No	Signal
1	UNREG +12V OUT
2	RXD/SD IN
3	TXD/SD OUT
4	GND

(3) 12VIN connector

(R03-R3M2) (Plug: R03-P3F)

Pin No	Signal
A	GND
B	UNREG +12V IN
C	NC

(4) TRIG connector

(HR10A-10R-12PB)

Pin No	Signal
1	GND
2	
3	
4	
5	GND
6	HD IN
7	VD/TRIG IN
8	
9	
10	GND
11	
12	GND

(5) Y/C connector

(TCS-7547-01-401)

Pin No	Signal
1	Y GND
2	C GND
3	Y OUT
4	C OUT

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8. Major accessories

1)	Camera control box	RC-Z3
2)	RS-232C level converter	JU-C20, JU-Z2

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9 when using lens

1) Projection (T) from flange face to rear of lens

Observe the lens mount size limit indicated in the figure. If too large, the lens and camera can be damaged

T: HV-D27A: Less than 3.8 mm  
 HV-D37A: Less than 4.3 mm

B

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2) Selecting lens

Overall camera lens make performance is largely affected by the lens. It is recommended to check the following points beforehand.

- Ghosting can occur by using a lens with a large image area (e.g. 2/3 or 1/2 inch for HV-D37A). Use a 1/2 inch lens for HV-D27A and 1/3 inch lens for HV-D37A.
- Vertical color shading can occur if the lens has a short exit pupil length.
- If the lens is used at nearly fully open iris, resolution is sacrificed, while such problems as shading and flare can detract from the image quality.

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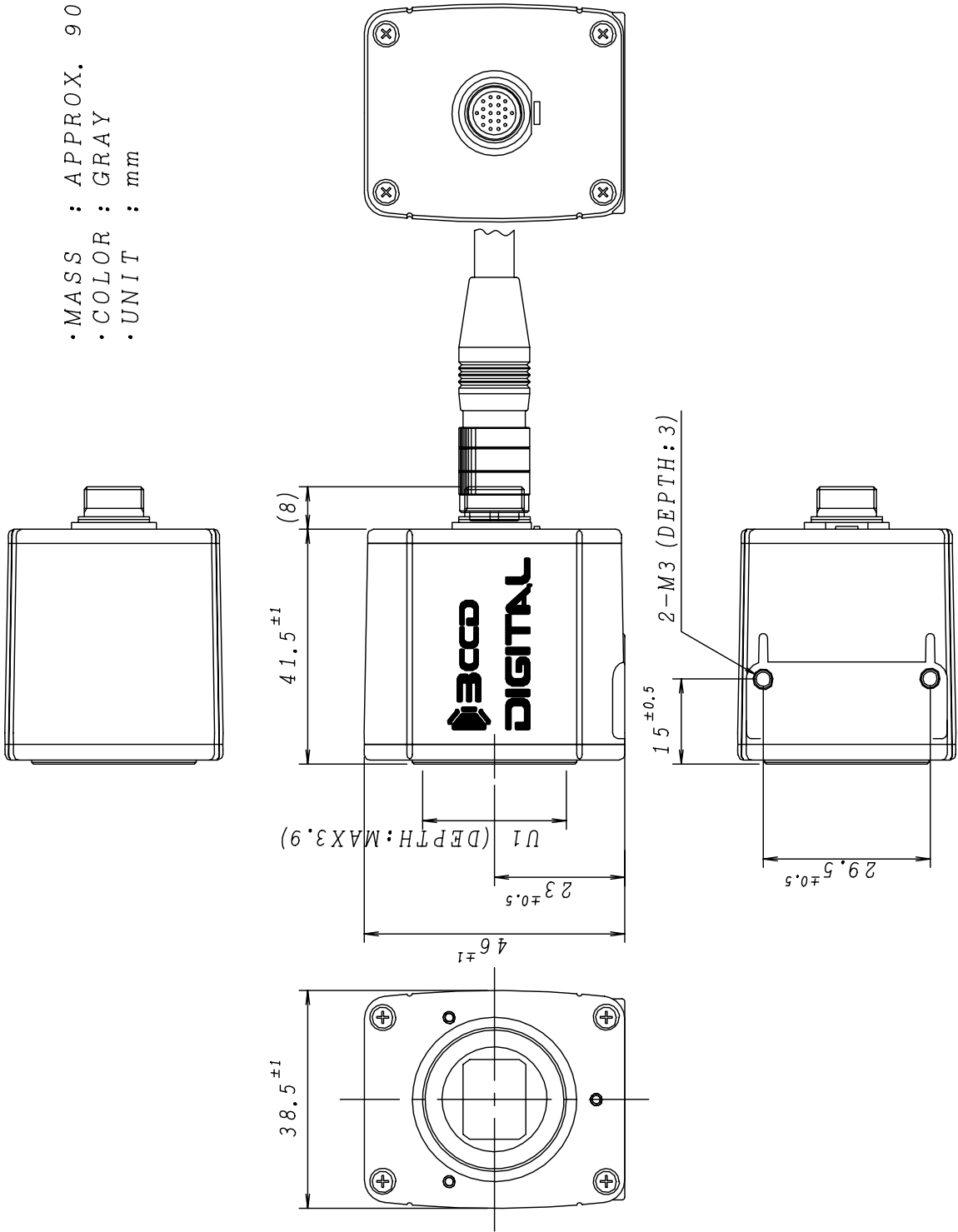
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10.Exploded view

(1) HV-D27A HEAD

•MASS : APPROX. 90 g  
 •COLOR : GRAY  
 •UNIT : mm

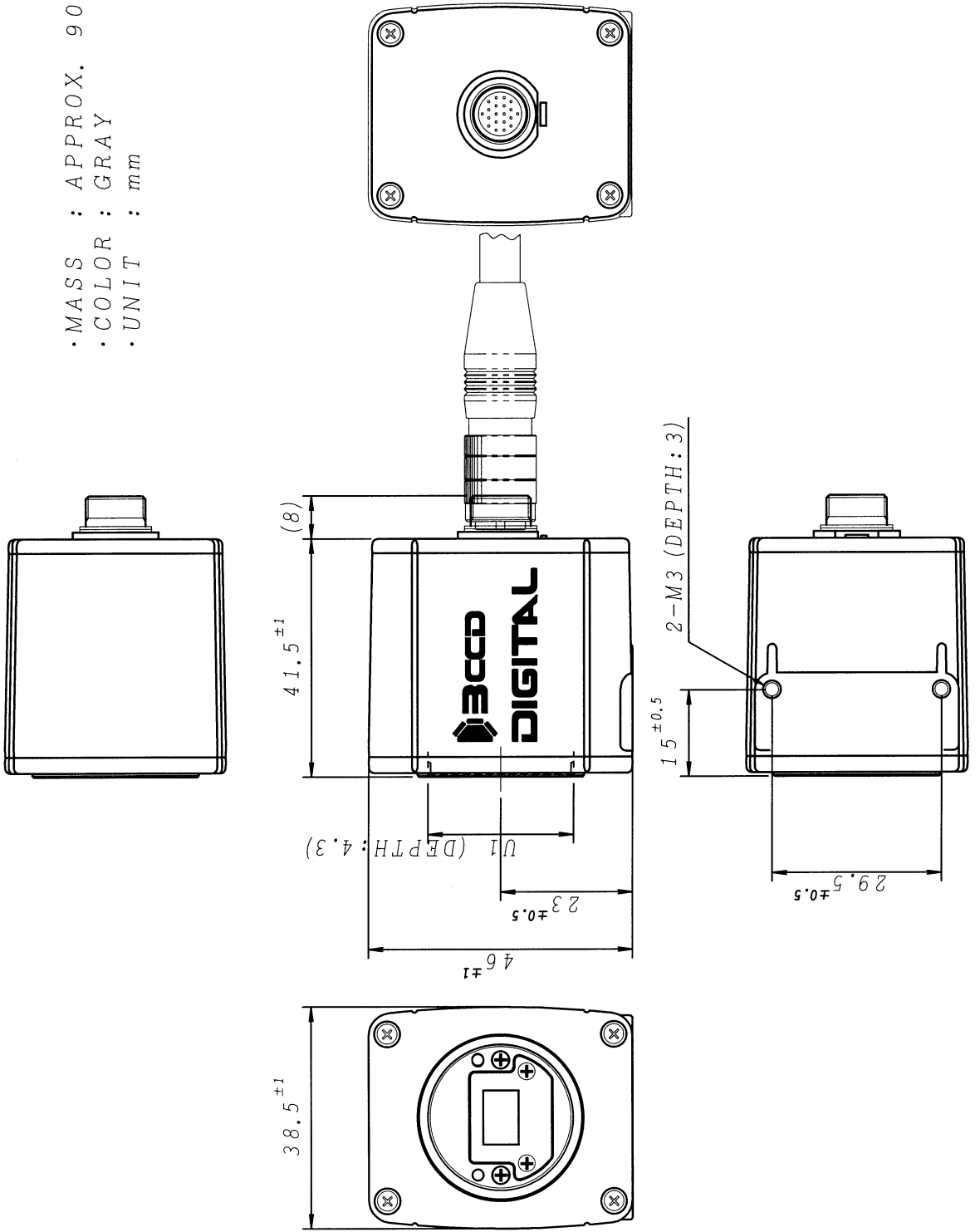


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(2)HV-D37A HEAD

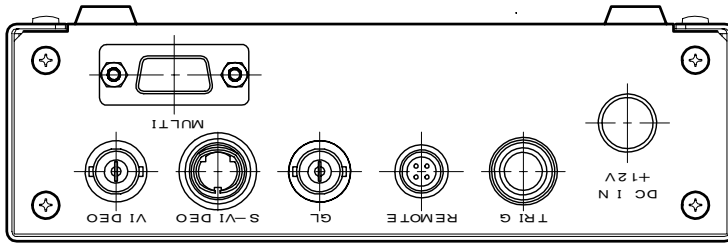
•MASS : APPROX. 90g  
 •COLOR : GRAY  
 •UNIT : mm



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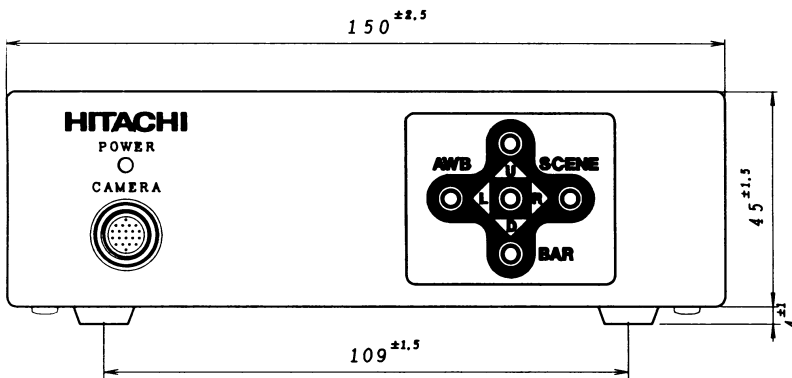
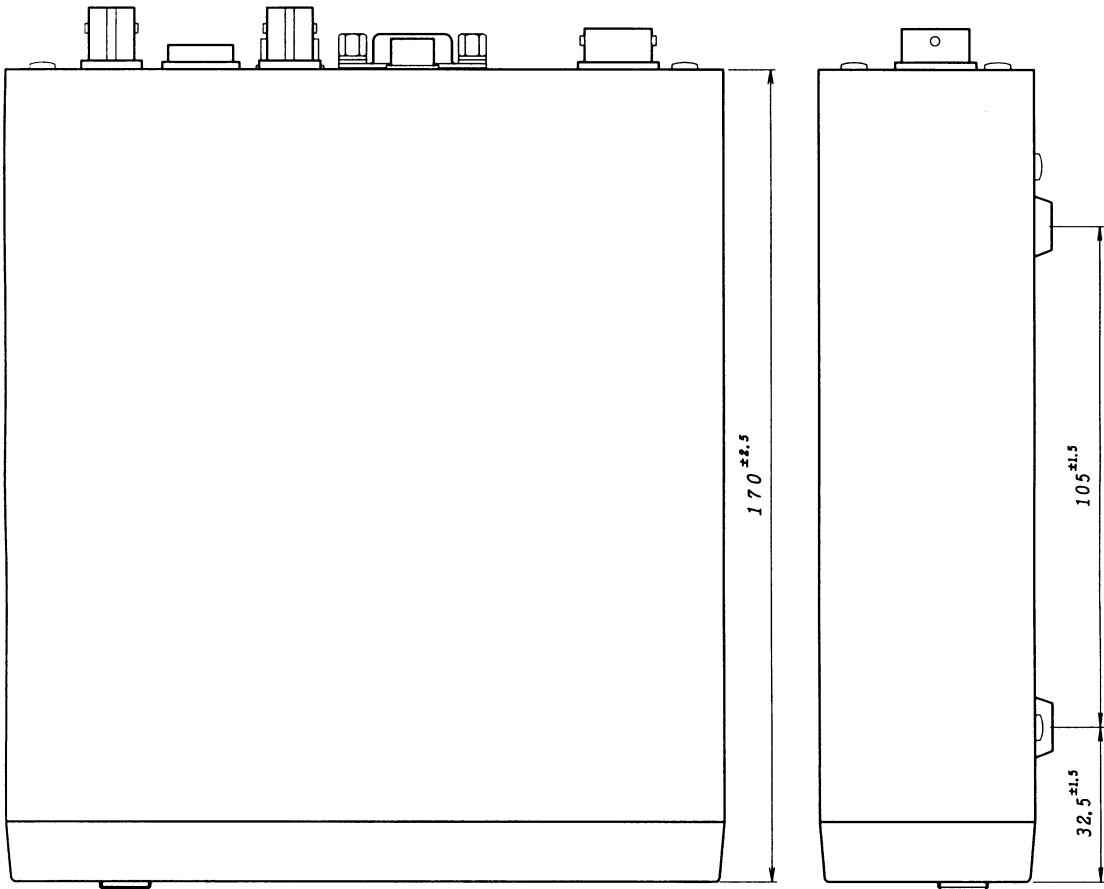
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(3) CCU



MASS: APPROX. 950 g

UNIT: mm



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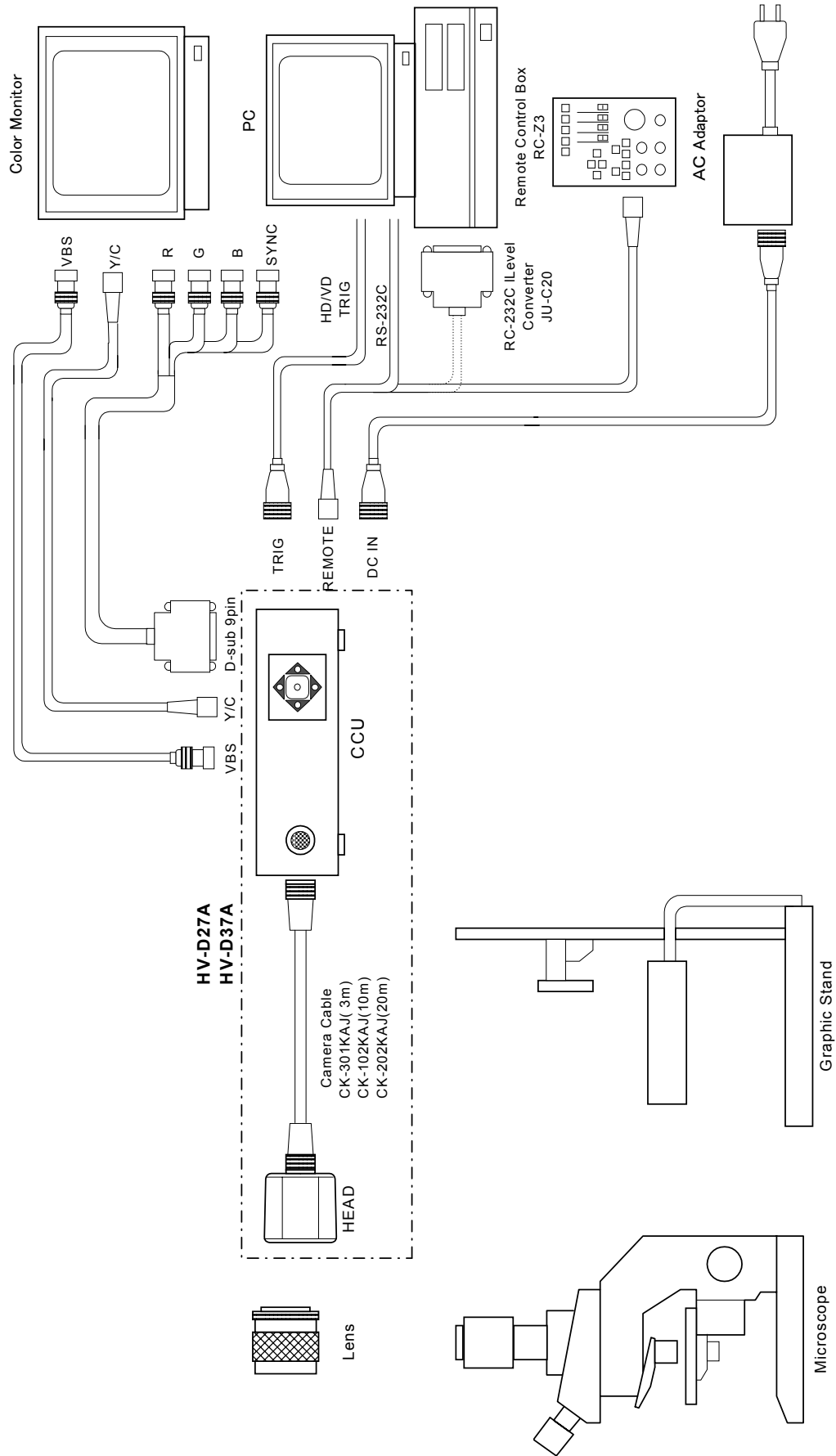
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11. System example



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